

Part of the Teledyne Imaging Group

Z-TRAK2 S-2K Series (Preliminary)

Factory Calibrated High-Performance 3D Profile Sensors



FEATURES

- » Scan speed 45K profiles/sec, 2,000 points/profile
- » Factory calibrated real-time measurements in real-world units
- » Unified Measurement Space for 360° in-line inspection and measurements
- » Handles highly reflected surfaces
- » Built-in reflection compensation algorithms
- » Multi-Sensor synchronization
- » Simplified cabling
- » Compact IP67 housing for harsh operating environment
- » Free bundled software:
 - » Sherlock[™] for rapid application deployment
 - » Sapera LT SDK for scan and control
 - » Sapera Pro run-times 1D, 2D and 3D image processing
 - » 3rd party software support for 3D image processing



The new Z-Trak2 family of 3D Profile Sensors delivers 45,000 profiles/sec for in-line measurement and inspection applications.

The Z-Trak2 S-2K Series combines speed and performance with easy to use software to deliver highly accurate, real-time results for a wide variety of 3D measurement and inspection applications in electronics, PCB, wafer, flat-panel, factory automation, food processing, and secondary battery markets.

The Z-Trak2 S-2K Series delivers 2K points per profile with a larger FOV and scan speeds beyond 45K profiles/sec. Combined with its hardware-based reflection compensation algorithms and single-scan HDR capabilities, the Z-Trak2 S-2K Series supports a variety of FOVs with blue and red laser configurations.

HIGH DYNAMIC RANGE (HDR) IMAGING

Powered by Teledyne's 3D image sensor technology, the Z-Trak2 family features built-in single-scan HDR capability. This allows Z-Trak2 to scan objects made of highly reflective surfaces like machine aluminum/glass and low reflectivity materials like rubber, plastic, etc. at the same time. The HDR capability helps reduce processing complexity and time, thereby improving system efficiency.

MULTI-SENSOR CONFIGURATION AND UNIFIED MEASUREMENT SPACE (UMS)

Multiple Z-Trak2 sensors can be combined and synchronized to create a unified measurement space, to measure an object in 360° or to eliminate occlusions. Multi-sensor synchronization can be accomplished using off-the-shelf Ethernet switches with better than $+/-1 \mu s$ precision. In addition, the Z-Trak2 series offers flexible connection topologies and a choice of calibration targets.





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SPECIFICATIONS

| Function | Description | |
|------------------------|---|--|
| Scanning Rate | • AOI: Up to 45,000 profiles/sec | |
| Connectors | 1 x M12 17-pin: Controls 1 x M12 8-pin X-Coded: Data Ethernet port 1 x M12 12-pin: Aux. I/O | |
| Image Enhancements | Single scan HDR Reflection elimination Specular configuration Filters: programmable median Horizontal and vertical flip Unified Measurement Space | |
| Multi-Sensor Sync | Single low-cost wiring using off-the- shelf network switches Sensor grouping Configuration wizard to ease timing setup | |
| Lasers | Red: 660n m 2M or 3R Blue: 405 nm 2M or 3R | |
| Reflectance Management | Time integration Laser power control: Automatic or manual Gain control | |
| Output Format | Individual profile, range map and 3D point cloud Depth (Z), Lateral (X), Reflectance (R) or Laser Peak Width (W) GenlCam 3.0 (SFNC 2.3) compatible 3D Data output formats compatible with Calibrated Z; Rectified Z, Calibrated ZR/ZR+W Native values and world units (microns/mm/inch) 16-bit mono (1D line-scan mode) 10-bit mono (2D area-scan mode) | |
| Temperature | Storage: -40°C to +80°C (-4°F to +176°F) temperature 20% to 80% non-condensing relative humidity Operating: 10°C (50°F) to 50°C (122°F) Relative Humidity: up to 90% (non-condensing) | |
| System Requirements | 5, 2.5 or 1 Gigabit Ethernet 4 GB or higher system memory | |

| Function | Description | | |
|---------------------------|---|--|--|
| 1/0 | 3 opto-isolated input Configurable as a trigger input or as a start/stop trigger 3 opto-isolated output Serial communication port or Analog output 4 – 20 mA | | |
| Encoder Input | Quadrature (AB) shaft-encoder inputs RS422/TTL Up to 20 MHz frequency Backlash compensation | | |
| Scan Control | Profile Trigger Encoder input, Internal timer/counter Fixed Scan External input; Software; Timer/counter Variable Scan Part in place; Start/Stop pulse | | |
| Unified Measurement Space | Intuitive GUI for rapid setup Up to 16 sensors Supports multiple sensors in side-by-side, circular and in-line configurations Combine red and blue laser models Supports models with different measurement ranges | | |
| Power Supply | PoE via 8-pin X-code circular connector (optional) Separate power via 12M 17-pin connector +12V to 36VDC +/-10% with surge protection | | |
| Enclosure | Machined aluminum IP67 4 x mounting holes | | |
| Software | Microsoft[®] Windows[®] 10 (32/64-bit) compatible Linux 32/64-bit: Ubuntu/Debian, RHEL/CentOS/Fedora, SLES/openSUSE Kernel: 2.6.32 or higher Fully supported by Teledyne DALSA's software packages (bundled free): Sherlock 8.0 Sapera LT 8.60 (or higher), Sapera Processing 8.0 (or higher) RTL Linux: Teledyne DALSA GevAPI Framework (SDK) ver. 2.40 or higher 3rd party software: MVTec[®] Halcon[®] NI[®] Max/Labview[®] Cognex[®] VisionPro[®] Stemmer CVB Application development using C++ and Microsoft .Net (C++, C# or Visual Basic) | | |
| Markings | FCC Class B, CE, ICE (pending) ROHS, China RoHS (pending) | | |



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| | Z-TRAK2 S-2K-0004 | Z-TRAK2 S-2K-0015 | Z-TRAK2 S-2K-0030 |
|----------------------------------|-------------------|-------------------|-------------------|
| DOF | 4 mm | 15 mm | 30 mm |
| Standoff (mm) | 15 | 55 | 65 |
| FOV (mm) | 9 - 10 | 23 - 27 | 46 - 57 |
| X-Res (µm) | 4.6 - 5.1 | 12-14 | 23 - 29 |
| Z-Res (µm) | 1 | 2 | 3 |
| Repeatability (<u>+</u> µm) | 0.25 | 0.35 | 0.4 - 0.5 |
| Linearity (<u>+</u>) % of F.S. | <0.025% | <0.025% | <0.02% |
| Laser (nm) | Blue405-2M | Blue405-2M | Blue405-2M |
| Options | 3R, Red660 | 3R, Red660 | 3R, Red660 |
| Interface | 5/2.5/1 GigE | 5/2.5/1 GigE | 5/2.5/1 GigE |
| Case Size | T10 | T20 | T20 |

| | Z-TRAK2 S-2K-0100 | Z-TRAK2 S-2K-0250 | Z-TRAK2 S-2K-0600 |
|----------------------------------|-------------------|-------------------|-------------------|
| DOF | 100 mm | 250 mm | 600 mm |
| Standoff (mm) | 90 | 180 | 380 |
| FOV (mm) | 95 - 157 | 166 - 325 | 428 - 978 |
| X-Res (µm) | 49 - 81 | 85 - 167 | 219 - 503 |
| Z-Res (µm) | 12 | 40 | 120 |
| Repeatability (<u>+</u> µm) | 0.75 - 1.25 | 2.5 - 6.0 | 7.5 - 15 |
| Linearity (<u>+</u>) % of F.S. | <0.02% | <0.02% | <0.02% |
| Laser (nm) | Red660-2M | Red660-3R | Red660-3R |
| Options | 3R, Blue405 | 2M, Blue405 | 2M, Blue405 |
| Interface | 5/2.5/1 GigE | 5/2.5/1 GigE | 5/2.5/1 GigE |
| Case Size | Т30 | Т30 | T40 |







Americas

Boston, USA +1 978-670-2000 sales.americas@teledynedalsa.com

Europe

Krailling, Germany +49 89-89-54-57-3-80 sales.europe@teledynedalsa.com

Asia Pacific

Tokyo, Japan +81 3-5960-6353 sales.asia@teledynedalsa.com Shanghai, China +86 21-3368-0027 sales.asia@teledynedalsa.com

www.teledynedalsa.com

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